

# Urban Air Mobility: Potential and Challenges Based on Research at the Institute of Aerospace Systems

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Kolloquium Urban Air Mobility: "Lieferdrohnen & Lufttaxis im Jahr 2025?" Aachen, July 16<sup>th</sup> 2024



#### Introduction

What is the first thing that comes to your mind when you think of Urban Air Mobility?

# Survey Results from Audience Poll on 16th July 2024

commercialization

Public acceptance

expensive

noise

financing

Safety

environment

Data collected via audience poll.

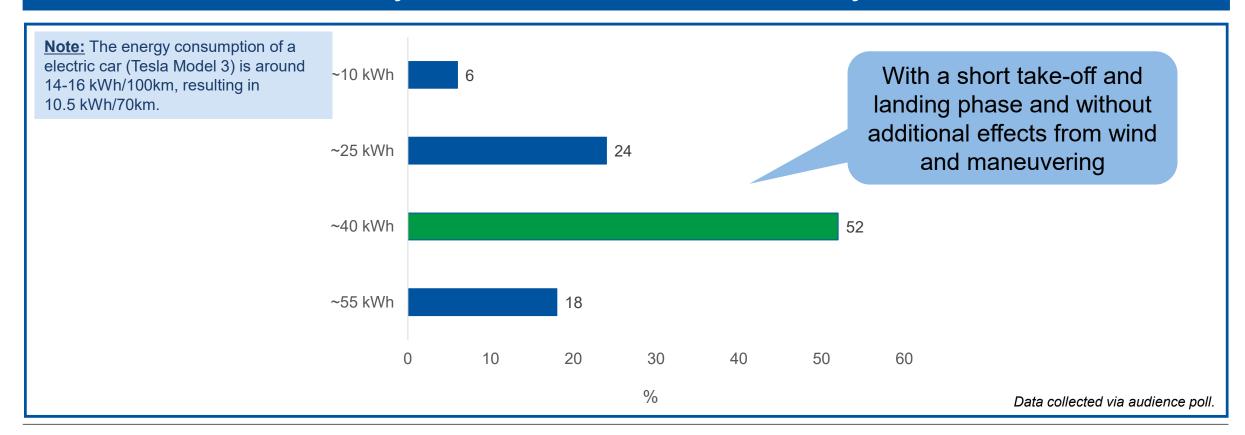




#### Introduction

# How high is the energy consumption of the Airbus A<sup>3</sup> Vahana vehicle concept? (Aachen-Cologne, 70km)

# Survey Results from Audience Poll on 16th July 2024



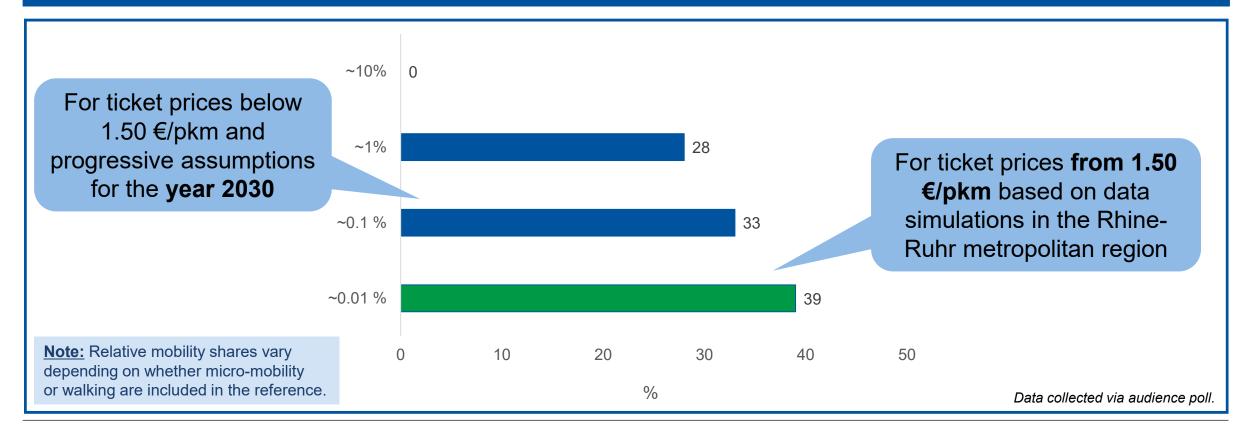




#### Introduction

Which modal split could UAM achieve (for a scenario with travel distances up to 100 km)?

# Survey Results from Audience Poll on 16th July 2024







### **Motivation**

#### Recent research

Vehicle Level UAM



Continuous development and analyses of eVTOL vehicles



Studies on vehicle performance



Noise emission reduction

Air Transportation System Level UAM



Market potential analysis



System modeling with competing modes of transportation



User and public acceptance

# Research questions -



Are UAM operations **feasible** and cost-efficient?





How can a **UAM network** be simulated and optimized?

How are piloted and autonomous UAM flights accepted?



Is UAM sustainable and brings **environmental benefits**?

We need a **scientific** approach including interdisciplinary research!





**eVTOL eVTOL Production** Certification **Station Planning Performance Mobility UAM Fleet Noise Emissions Total Costs Simulation Simulation Ticket Pricing Business Case User Acceptance** CO<sub>2</sub>e **Technical Foundation Operational Analysis Overall Evaluation Environmental Impact** Market & Social Factors





1

Certification







# Certification

#### **Current status**

- Regulatory framework: EASA and FAA are developing guidelines for eVTOL certification
- **Pilot projects:** Test flights in urban areas, including demonstration flights with approvals (e.g. Ehang)
- **Technological advancements:** Development and testing of autonomous flight systems



# **Future requirements and development**

- Certification process: Implementation of a phased based approach by EASA and FAA for eVTOL
- Infrastructure requirements: Essential for skyport construction and station network planning
- eVTOL downwash/outwash: Safety zones due to the downwash effects caused by vehicles





Certification

eVTOL Performance







# **eVTOL** Performance

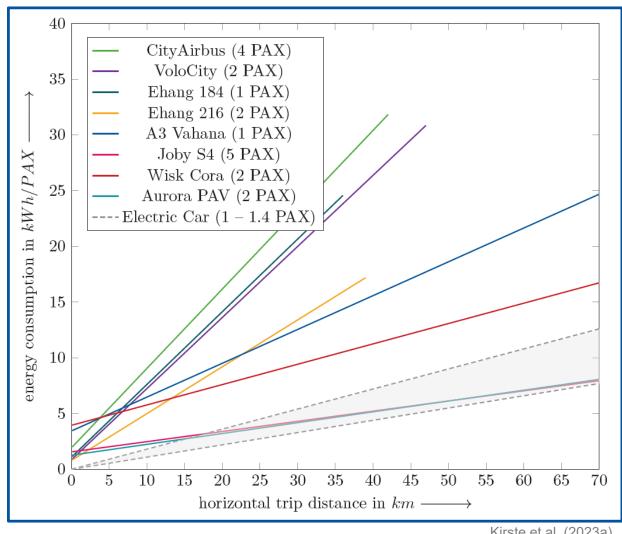
eVTOL vehicles

Configuration	PAX			
Multicopter	4			
Multicopter	2			
Multicopter	1			
Tilt-Wing	1			
Tilt-Rotor	5			
Lift + Cruise	2			
Lift + Cruise	2			
	Multicopter  Multicopter  Multicopter  Tilt-Wing  Tilt-Rotor  Lift + Cruise			

Note: There are many more eVTOL vehicles, including cases for passenger transport, emergency assistance, and logistic of goods.

Findings -

"perfect" eVTOL configuration for efficient UAM fleet operations unclear



Kirste et al. (2023a)





Certification

<sup>2</sup> eVTOL Performance

Station Planning



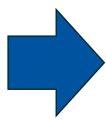




# **Station Planning**

# How it is often analyzed

- Optimization based on mobility demand data
- K-means clustering of similar demand patterns
- Constraints:
  - Accessibility
  - Capacity
  - Peak hour performance



#### How it could be enhanced

- Input of simulated **UAM demand** and scenarios
- Theoretical best stations as option for further studies
- Individualized analysis of each station option:
  - Property ownership
  - Take-off and landing constraints
  - Connection to other modes of transportation





Certification

<sup>2</sup> eVTOL Performance

Station Planning

eVTOL Production





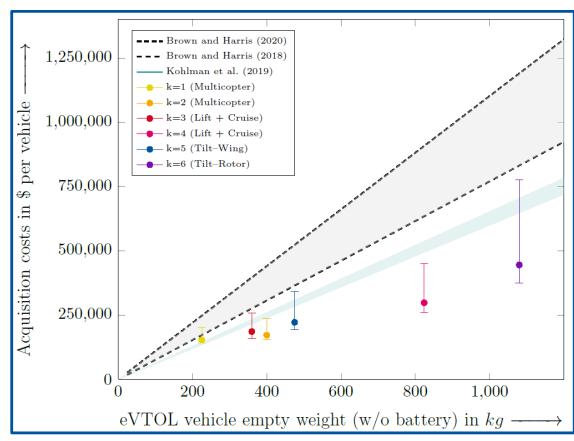


# **eVTOL Production**





- Empty mass dependent linearization approaches
- Calibration of parametric models is decisive
- Impact of production volume is most decisive



Kirste & Stumpf (2024a)





Certification

eVTOLPerformance

Station Planning

eVTOL Production

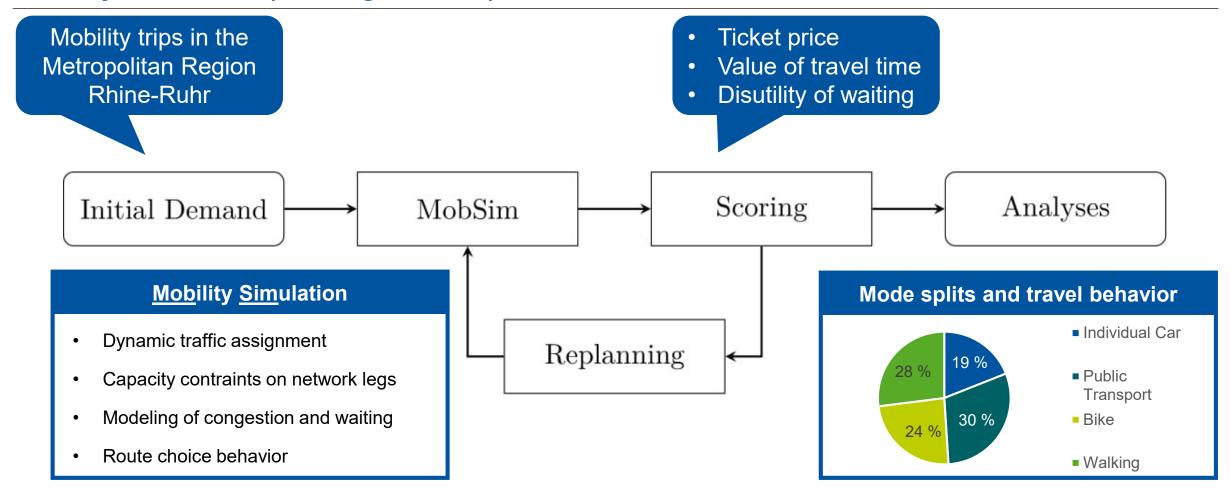
MobilitySimulation







# **Mobility Simulation (utilizing** *MATSim***)**



MATSim iterative optimization process based on: Horni et al. (2016)





Certification

<sup>2</sup> eVTOL Performance

Station Planning

eVTOL Production

MobilitySimulation

<sup>6</sup> UAM Fleet Simulation

Technical Foundation
Operational Analysis
Environmental Impact
Market & Social Factors

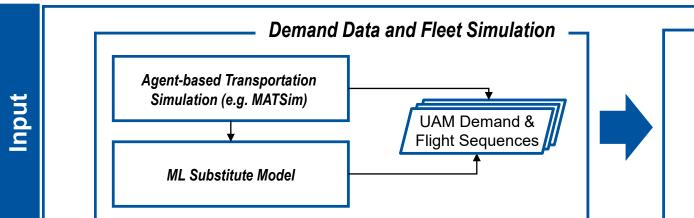




#### Interdisciplinary Research Project ACCESS!\*

- user acceptance
- other modes of transport
- specific scenario





Air Transportation System UAM —

Postprocessing

- Cost Optimization
- Pricing Strategies
- Sustainability Aspects
- Vehicle Design

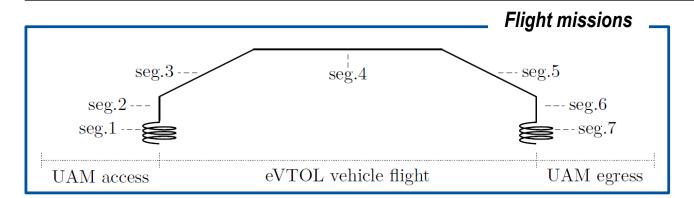
# **Aircraft Design**

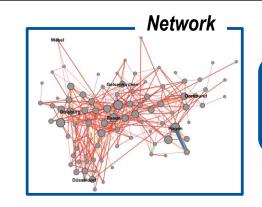
\* https://www.accessnrw.rwth-aachen.de/





## **UAM Fleet Simulation**

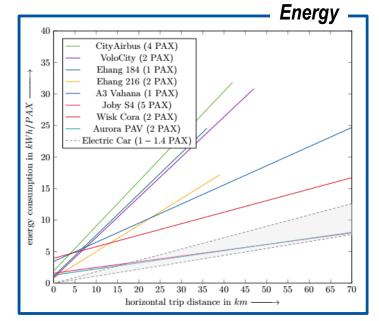


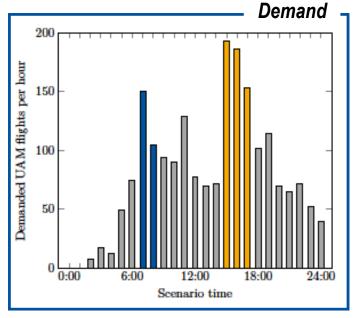


Base Case of Rhine-Ruhr simulation with MATSim

|--|

eVTOL vehicle	Configuration	PAX
City Airbus	Multicopter	4
VoloCity	Multicopter	2
Ehang 184	Multicopter	1
A3 Vahana	Tilt-Wing	1
Joby S4	Tilt-Rotor	5
Wisk Cora	Lift + Cruise	2
Aurora PAV	Lift + Cruise	2





Figures from Kirste et al. (2023a), Kirste & Stumpf (2023b), and Kirste & Stumpf (2024b)





Certification

<sup>2</sup> eVTOL Performance

Station Planning

eVTOL Production

MobilitySimulation

6 UAM Fleet Simulation

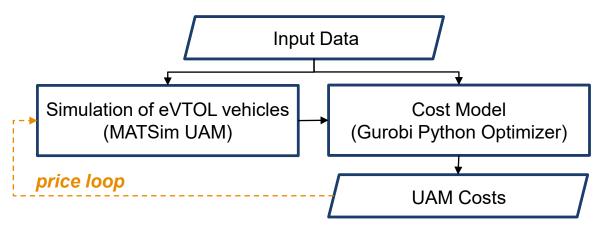
Total Costs

Technical Foundation
Operational Analysis
Environmental Impact
Market & Social Factors



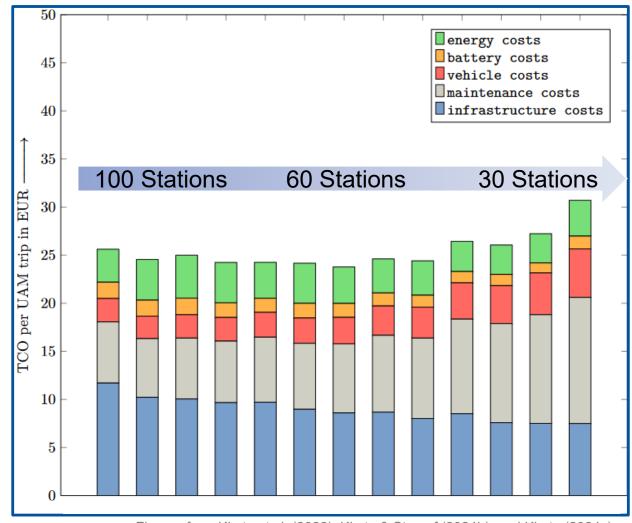


## **Total Costs**



**Findings** 

- For a **medium station density**, total UAM costs are around **1.50 €/pkm** (optimized)
- Feasible operation can only be found within 1.20 to 1.70 €/pkm
- Piloted flight operations are cost-inefficient in a considered cases of the study scenario



Figures from Kirste et al. (2022), Kirste & Stumpf (2024b), and Kirste (2024c)





Certification

<sup>2</sup> eVTOL Performance

Station Planning

eVTOL Production

MobilitySimulation

6 UAM Fleet Simulation

Total Costs

**Noise Emissions** 







## **Noise Emissions**

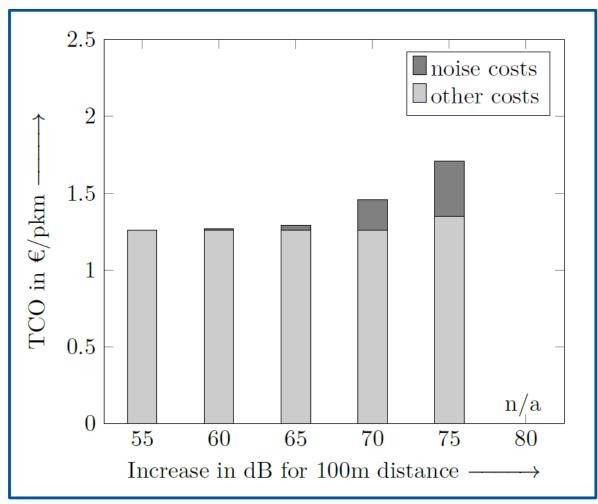


- Hedonic pricing method
- Number of real estate properties are linked to each vertiport option
- Noise costs result from the number of flight affecting the properties and their noise levels

**Note:** The assessment of noise emissions from drones is not solely dependent on the sound level. It is also influenced by subjective perception and the frequency of flight operations. This approach represents a simplification of the broader research field.

# **Findings**

- 75 dB noise emission for 100 m distances are critical
- Different station placements are considerable for feasable operations



Kirste et al. (2023a)





Certification

eVTOLPerformance

Station Planning

eVTOL Production

MobilitySimulation

UAM Fleet Simulation

Total Costs

**Noise Emissions** 

CO2e

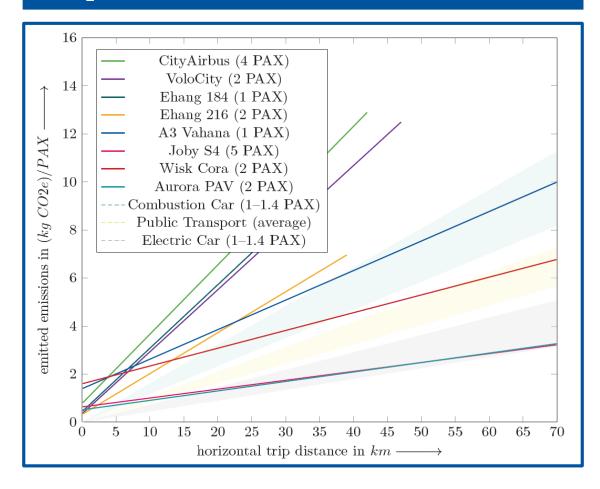




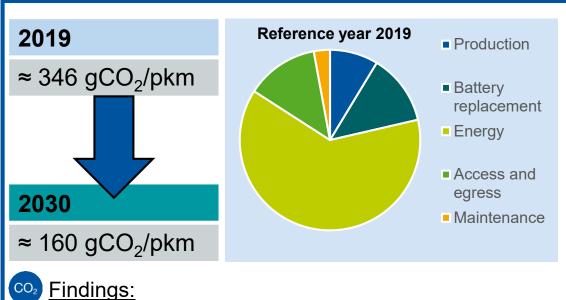


#### **Environmental assessment**

# CO<sub>2</sub> emissions for different transport modes



# Life cycle emissions for UAM



- - At present, eVTOL operations cannot be considered environmentally sustainable
- An increased share of green electricity could significantly reduce the ecological footprint of UAM

Kirste et al. (2023a)





1 Certification

eVTOLPerformance

Station Planning

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MobilitySimulation

UAM Fleet Simulation

Total Costs

**Noise Emissions** 

CO2e

User Acceptance

Technical Foundation
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# **User Acceptance / User Preferences**

# General survey design

#### "Would you fly with an air taxi?"

- Advantage: Many survey responses
- Disadvantages:
  - Potential bias due to lack of comprehensive information about air taxi operations
  - User attitude does not necessarily correspond to user behavior

### **Findings**

- Noise and safety are common general concerns
- Higher acceptance for search and rescue missions as well as emergency flights
- Support for passenger transport is increasing but remains significantly lower

# **Choice-based-Conjoint (CBC) study design**

Attribute	Option 1	Option 2	Option 3
Skyport	Airport	Rural area	Urban area
Price	56 €	68€	83 €
Automation	Pilot remote	Pilot on-board	Autonomous
Environmental Impact	1.5 times the status quo	2 times the status quo	0.5 times the status quo
Extras	W-Lan	Radio	Special seat

#### **Findings**:

- > **Key attributes:** Price and travel time are identified as the most significant attributes
- ➤ Environmental friendliness: When explicitly asked about environmental friendliness, it is considered highly relevant by respondents

Results and survey design examples are partly based on: Tepylo et al. (2023), and Lotz et al. (2023)





1 Certification

eVTOLPerformance

Station Planning

eVTOL Production

MobilitySimulation

6 UAM Fleet Simulation

Total Costs

**Noise Emissions** 

CO2e

User Acceptance

Ticket Pricing

Technical Foundation
Operational Analysis
Environmental Impact
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# Ticket Pricing (Case study simulation Rhine-Ruhr)

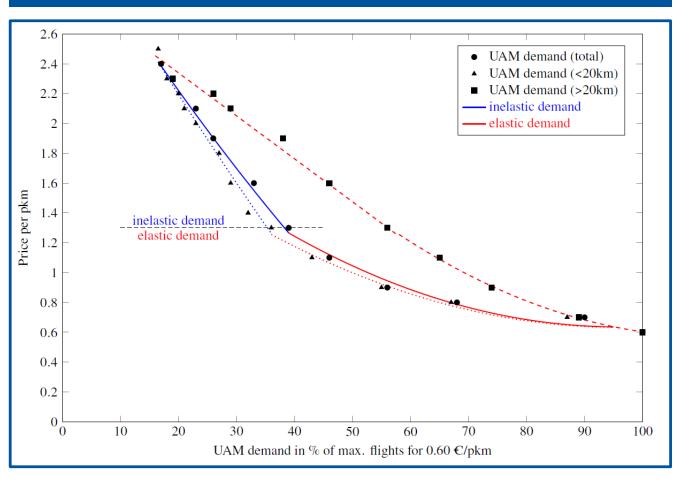
#### Simulation of Rhine-Ruhr scenario

- 1% simulation scenario (MATSim)
- 100 iterations to enable innovative **UAM flights**
- Cruise speed depending on eVTOL vehicle (e.g. 150-200 km/h for Tilt-X configurations)
- Average process times of 15 min per UAM trip

# **Findings**

- Elastic demand for longer flights (>20km) and for prices ≤ 1.30 €/pkm
- Ticket prices should vary based on trip length and time of request

# **Price Elasticity**



Kirste & Stumpf (2024b)





1 Certification

eVTOLPerformance

Station Planning

eVTOL Production

MobilitySimulation

UAM FleetSimulation

Total Costs

**Noise Emissions** 

CO2e

User Acceptance

Ticket Pricing

Business Case

Technical Foundation
Operational Analysis
Environmental Impact
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# **Business Case (Case study simulation Rhine-Ruhr)**

#### Input

#### Sets

- eVTOL vehicle concepts, pricing options, time
- ➤ UAM fixed base price: 0 12 €
- Variable price: 0 2.50 €/pkm

#### **Decision Variables and Constraints**

- Vehicle concept
- Binary variable for price setting
- Constraints: One pricing option per time period

## Parameters (sample)

- Energy costs: 0.30 €/kWh
- Maintenance costs: 50 €/FH
- Battery and autonomy assumptions for 2030

eVTOL vehicle	Pricing	Profit in %
Aurora PAV	static	7.7
	dynamic I	15.3
	dynamic II	24.0
Airbus A <sup>3</sup> Vahana	static	- 4.1
	dynamic I	3.1
	dynamic II	15.4
Ehang 216	static	- 11.1
	dynamic I	- 3.9
	dynamic II	4.2
VoloCity	static	- 50.0
	dynamic I	- 22.0
	dynamic II	- 10.4

**Note:** The complete model includes additional cost parameters and constraints. Also, technology developments for 2030 are assumed.

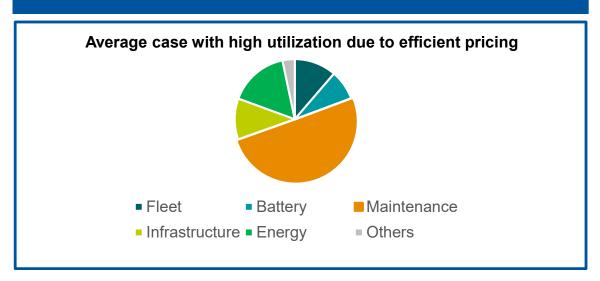
Kirste & Stumpf (2024b)





# **Business Case (Case study simulation Rhine-Ruhr)**

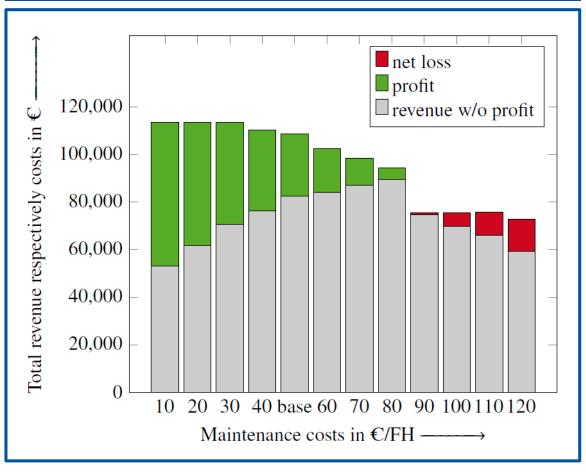
#### **Total costs**



# Findings

- Business cases are currently dependent on many uncertainties
- Increase in eVTOL fleet utilization (+ 10 % rkm) and profit for temporal dynamic pricing
- Maintenance costs at most 80 €/FH are decisive

# **Sensitivity of maintenance costs**



Kirste & Stumpf (2024b)





**eVTOL eVTOL Production** Certification **Station Planning Performance Mobility UAM Fleet Noise Emissions Total Costs Simulation Simulation Ticket Pricing Business Case User Acceptance** CO<sub>2</sub>e **Technical Foundation Operational Analysis Overall Evaluation Environmental Impact** Market & Social Factors





#### **Evaluation**

#### **Potential**

- Faster mode of transportation utilizing the third dimension
- Initial implementation of airport shuttles and demonstration flights
- Short-term potential with governmental support (e.g. in metropolitan regions in Asia)
- Feasible business cases for progressive technology development by 2030
- Potential for emergency medical services

# Challenges

- Autonomous eVTOL flights are decisive for feasible fleet operations
- Regulatory hurdles remain
- Large-scale implementation unclear
- UAM is in competition with Intelligent Transport Systems (ITS)
- Public acceptance among non-users
- Noise emissions and eVTOL downwash effects
- > UAM is currently either strongly criticized or hyped (in Germany)
- > UAM is scenario-specific, but has to be further developed and analyzed
- Successful implementation requires collaboration among all stakeholders





# Thank you



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