

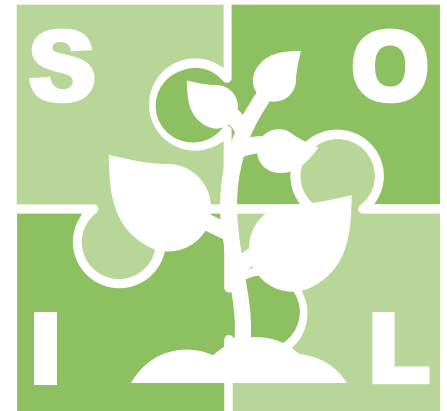
SOIL - SensOr Interfacing Language: Light-weight universal data model for FAIR Industrial Sensor Data

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10.08.2023

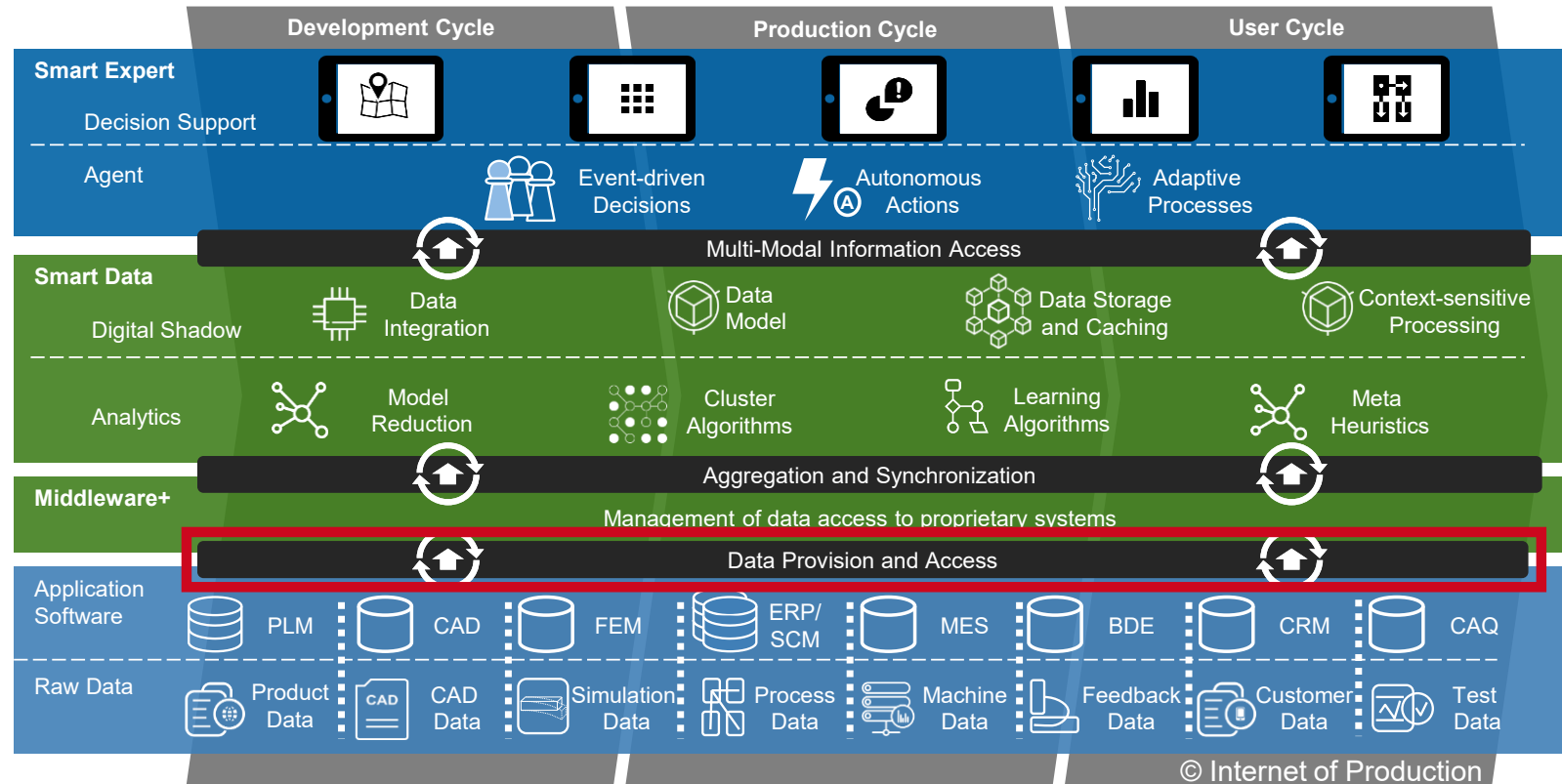
**SensOr Interfacing
Language**



FAIR Sensor Data by Default

Introduction

Needs for Long-Term Reusability of Sensor Data



Making data-based decisions

Turning data in value

Deriving knowledge from data

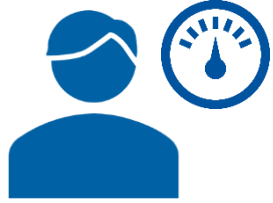
Data aggregation

Heterogeneity of data sources

Very high amount of data

Industry demands for interoperable data models and interfaces

- | | |
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| 1 | Introduction |
| 2 | Designing Interfaces |
| 3 | SensOr Interfacing Language |
| 4 | Conclusion |



Sensor expert



Network expert



Data steward



Proprietary data package
and protocol
...
216424524131765722
134765243134265724
316425727341642572
14324645
...

Manufacturer-specific interface

Technically interoperable interface

Semantically interoperable interface

```
{
  "uuid": "VAR-Position",
  "name": "Position",
  "description": "Most recently dispatched measured position.",
  "datatype": "double",
  "value": [
    -0.3847837151452236,
    6.722830908191401,
    0.2103853768765931
  ],
  "dimension": [
    3
  ],
  "range": [
    null,
    null
  ],
  "timestamp": "2020-11-13T10:44:36.523Z",
  "nonce": "Kalibrierung einer Werkzeugmaschine",
  "covariance": null,
  "uncertainty": [0.0001230, 0.0001468, 0.0001395],
  "unit": "MTR",
  "ontology": null
}
```

{ REST } MQTT.ORG

```
acquisition.ttl
77 radian:TargetPosition
78   qudt:hasQuantityKind quantitykind:Length ;
79   qudt:applicableUnit unit:M ;
80   ssn-system:hasSystemCapability radian:TargetRange ;
81   sem:hasTimeStamp "2021-11-02T13:56:38.532Z" ;
82   qudt:standardUncertainty ("0.0008869218"^^xsd:float "0.000
83   schema:value ("-0.226959617"^^xsd:float "-0.3074850568"^^
84   rdfs:label "Kalibrierung einer Werkzeugmaschine" .
```

FAIR Sensor Service



Production Engineer

- Device knowledge
- Process knowledge

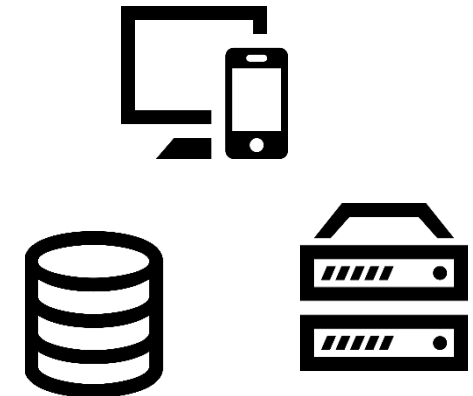
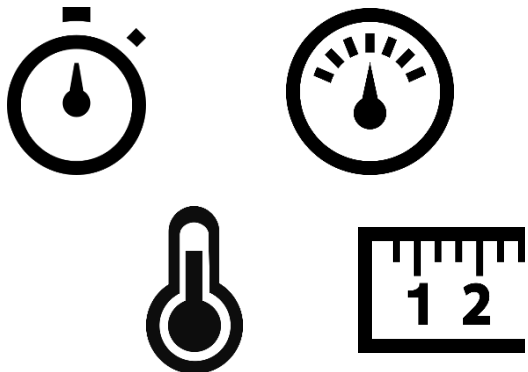


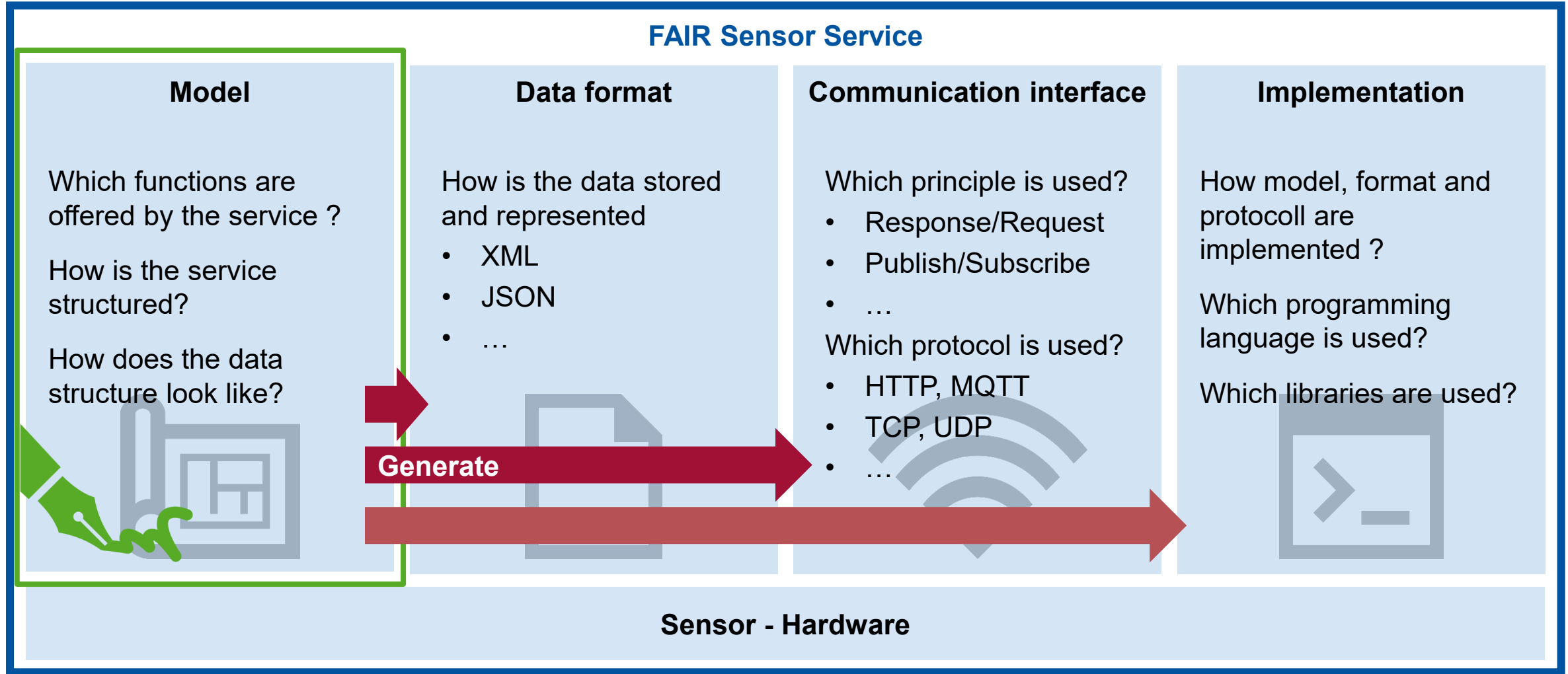
Computer Scientist

- Protocol knowledge
- Network knowledge

Domain-specific Modeling Language

„Gap of knowledge“





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Interoperable Measurement Data

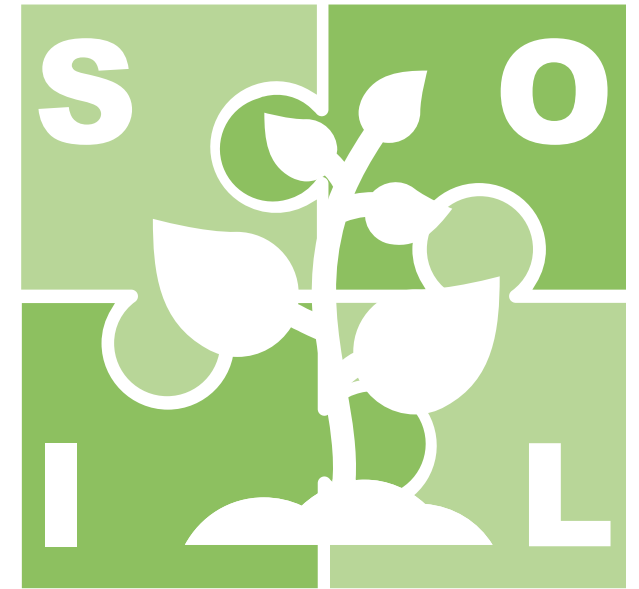
Definition of modern high-level data models

Data structure, format and communication protocol can be fully generated

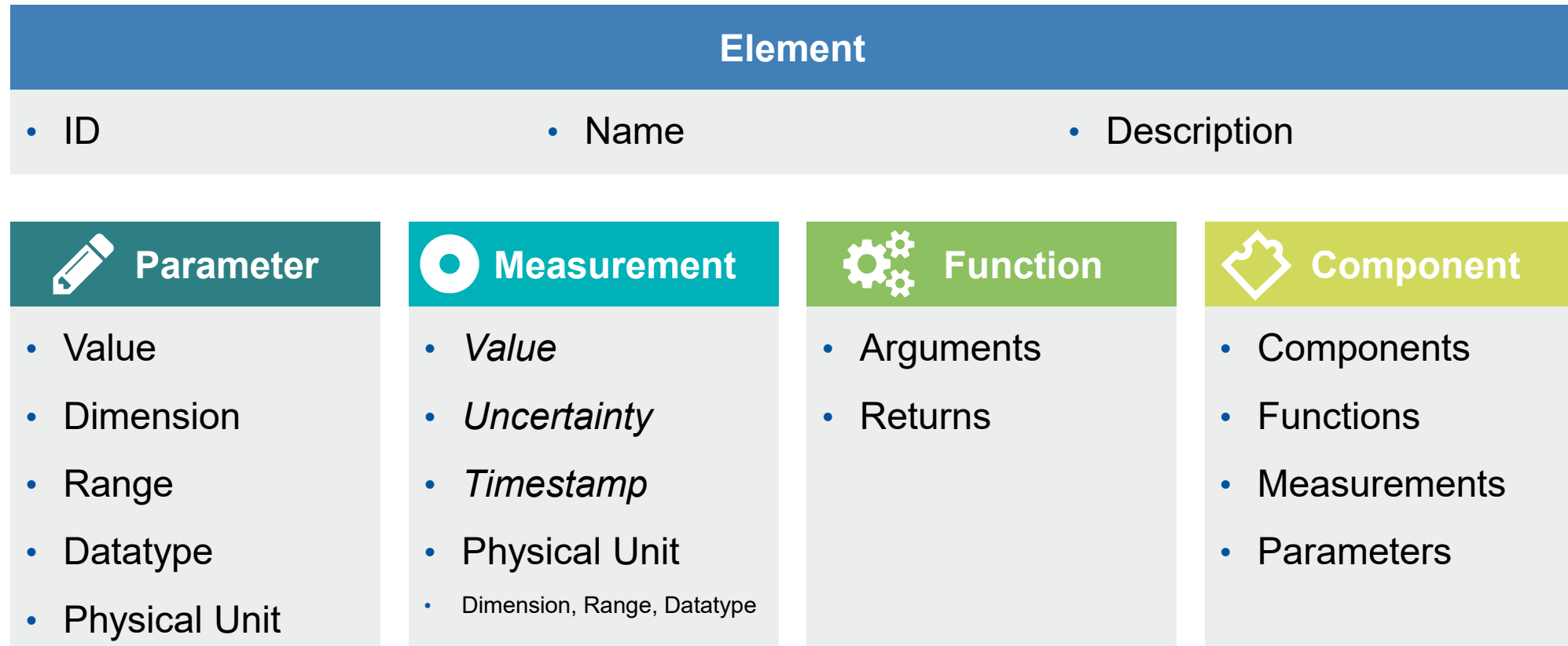
Context and meta information are automatically inherited in data packages

Visual and textual web editor for (non-) programmers

SensOr Interfacing Language



FAIR Sensor Data by Default



```
measurement Temperature {
  name: "Ambient temperature"
  description: "The current ambient temperature."
  datatype: float
  range: (-20, 50)
  dimension: []
  unit: Celsius
}

component EnvironmentalSensor {
  name: "Environmental Sensor"
  description: "A single wireless environmental sensor, measuring temperature, pressure and humidity."
  measurements:
    Temperature temperature

  streams:
    temperature: fixed(5)
}

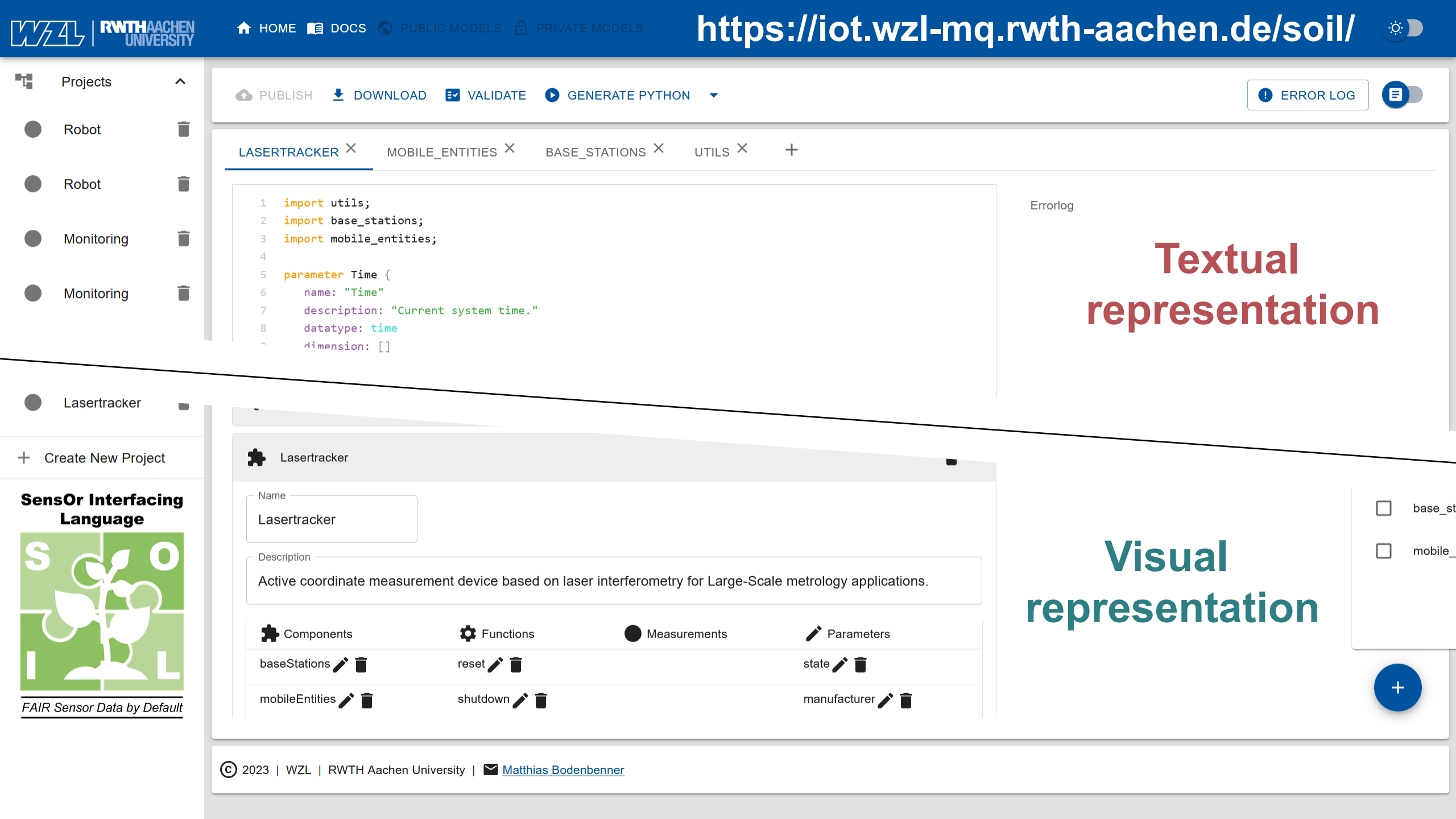
interface EnvironmentalSensor MySensor {}
```



M. Bodenbenner:

Description and Manual of the *SensOr Interfacing Language*

Zenodo - <https://doi.org/10.5281/zenodo.7757249>



```
1 import utils;
2 import base_stations;
3 import mobile_entities;
4
5 parameter Time {
6     name: "Time"
7     description: "Current system time."
8     datatype: time
9     dimension: []
10 }
```

Errorlog

Textual
representation

Lasertracker

Name
Lasertracker

Description
Active coordinate measurement device based on laser interferometry for Large-Scale metrology applications.

Components

baseStations

mobileEntities

Functions

reset

shutdown

Measurements

Parameters

state

manufacturer

Visual
representation

base_st
mobile_



SOIL Editor

```
1 import utils;
2 import base_stations;
3 import mobile_entities;
4
5 parameter Time {
6   name: "Time"
7   description: "Current system time."
8   datatype: time
9   dimension: []
10 }
```

Lasertracker

Name
Lasertracker

Description
Active coordinate measurement device based on laser

Components **Functions**

baseStations	reset
mobileEntities	shutdown



Server-Backend

- SOIL Parser
- SOIL Validator
- SOIL Generator

Template for implementation

```
class COMLasertrackerTOP(object):
    def __init__(self, device: Device, state: State = None,
                 time: datetime = None):
        self._device = device
        self._par_state = state
        self._par_manufacturer = manufacturer
        self._par_version = version
        self._par_time = time
        self._com_basestations = COMBaseStations(device)
        self._com_mobileentities = COMMobileEntities(device)

    usage
    def get_par_state(self) -> State:
        return self._par_state

    def set_par_state(self, state: State):
        self._par_state = state

    def get_par_manufacturer(self) -> str:
        return self._par_manufacturer

    def get_par_version(self) -> int:
        return self._par_version

    def get_par_time(self) -> datetime:
        return self._par_time
```



Complete implementation

```
class COMLasertracker(COMLasertrackerTOP):
    def __init__(self, device: Device, state: State = None,
                 time: datetime = None):
        COMLasertrackerTOP.__init__(self, device, state, time)
        self._com_basestations = COMBaseStations(device)
        self._com_mobileentities = COMMobileEntities(device)

    def fun_reset(self):
        self._device.reset_tracker()

    def fun_shutdown(self):
        self._device.stop()

    def get_par_state(self):
        return str(self._device.state)

    def get_par_time(self):
        return datetime.datetime.now()
```



FAIR Sensor Service



➡ Manual implementation of the sensor logic
➡ Automated generation

 **MQTT-Library**

 **REST-Library**

```
{
  "covariance": [
    [1.3276206530821578e-10, 1.0791437929694123e-11, 7.9915972948561065e-11],
    [1.079143792969412e-11, 5.5091565613752213e-11, 1.0896977314156854e-11],
    [7.9915972948561065e-11, 1.0896977314156854e-11, 5.9079887330941402e-11]
  ],
  "datatype": "float",
  "description": "Position in Cartesian Coordinates in meter.",
  "dimension": [3],
  "hash": "3a785573eecfc75434572906c31bae675f1c173612bc25579c996bddf4e51a85",
  "label": "Calibration of machine tool.",
  "name": "Position [m]",
  "range": [-40, 40],
  "timestamp": "2022-06-13T11:27:15.046550Z",
  "unit": "MTR",
  "uuid": "MEA-Position",
  "value": [2.4184784967537318, 0.32977268925781256, -3.8299400458421968]
}
```

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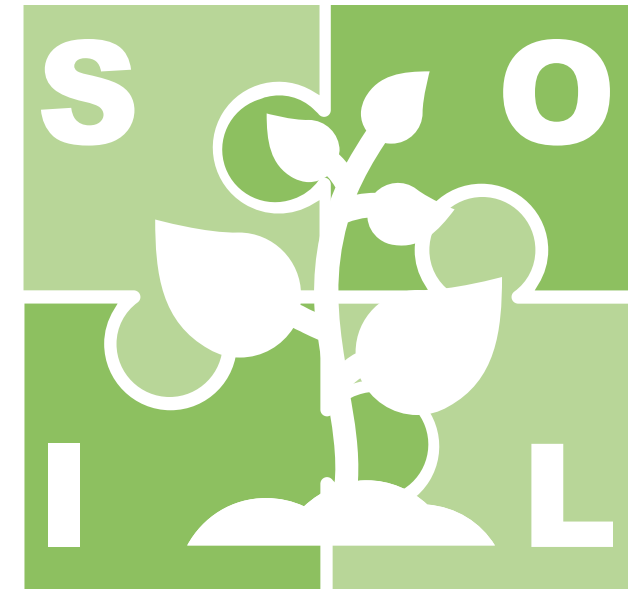
Summary

- *FAIR Sensor Services* adopt the FAIR Guiding Principles for industrial sensor data
- *SensOr Interfacing Language* provides easy-to-use modeling framework
- Approach effectively decouples modeling and integration

Outlook

- Adopting existing terminology
 - e.g., Semantic Sensor Network Ontology
- Full semantic mapping of the SOIL meta model
- Mapping to widely applied models (OPC UA, AAS)

SensOr Interfacing Language



FAIR Sensor Data by Default

Thank you very much



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Funded by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) under Germany's Excellence Strategy – EXC-2023 Internet of Production – 390621612.

Funded by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) under Project-ID 432233186 – AIMS.

Funded by
 **Deutsche
Forschungsgemeinschaft**
German Research Foundation